

DS18B20 jmkkd h_ hibkZgb_ jZ[hlu k ^Zlqbdhf l_

MEGETEX

Q_jgh\ =_ggZ^b

Подключение DS18B20 в режиме внешнего питания рис 5.

64-BIT код датчика

```

DZ`^uc '6 % kh^_j`bl mgbdz bmguc dh^ jkk khojZg_gguc \ 520 FeZ^rb
[blh\ dh^Z 520 kh^_j`Zl dh^ k-Wirecik\Z^hf '6 % 2Bv. Ke_^mxsb_ [blh\ kh^_j`
mgbdz evguc k_jbcguc ghf_j KlZjrb_ [blh\ kh^_j`Zl pbdebq_kdh]h dhgljhey b
dhlhjuc \uqbke_g hl i_j\uo [blh\ dh^Z 520 >_lZebabjh\Zggh_ h[tykg_gb
dhgljhey ba[ulhqghklb h[_k\jZaZ GENERATION pbdebq_kdh]h dhgljhey ba[ulhqgh
[blh\uc dh^ 520 b k\yaZggZy nmgdpby 520 mijZ\eyxl eh]bdhc iha\h e-Wire '6 %
mkljhckl\h bkihevamy ijhlhdhe ^_lZebabjh-WIREBUS SYSTEM_ve\hc lZ[ebpu ^Zgguo
    
```

64-BIT LASERED ROM CODE j b k6

ПАМЯТЬ

```

lZfyly '6 % ¶V hj]Zgbah\ZgZ dZdj bkd Z Zyglv kkhkhlbl ba hi_$RAM gZhfylb b
wg_]hg_aZ\bkbfhc EEPROM l_j\u_ ^Z j_]bkljZ wlh j_]bklju dhg\_jlhJZ l_fi_jZl
b^mj_]bklju :\Zjbbjog_]h b gb`g_]h H and Z b j_]bklj dhgnb]mjZpbb H[jZlbl_\g
qlh _keb nmgZpby 6 % g_ bkihevalm_jlk]bklj H and TL fh]myq_cdZrb\_jkZevghc
iZfyb <k_dhfZg^u iZfyly hibkZgu ih^jh FUNCTIONAL COMMANDS DS18B20.
;Zcl b [Zcl HAM h^_j`bl feZ^rb bkljrb]bl l_fi_jZlmjgh]h j_]bkljZ khh\_\kl\_g
[Zclu lhevdh ^ey ql_gby ;Zclu b h[_kijq]b\ZjZ H and TL dZcl kh^_j`bl ^Zgguo
j_]bkljZ dhgnb]mjZpbb dhlju_ h[tykgyxky ih^jh[gh \ jZa^_e_ J?=BKLJ
(CONFIGURATION REGISTER) wlhc lZ[ebpu ^Zgguo ;Zclu b aZj_a_j\bjh\Zgu ^
bkihevah\Zgby mkljhckl\hf\ bwlZjbb]bklju g_\hafh`gZ ijb ql_gbb wlb [Zclu \ha\
\k_o jZajy^Zo
8;Zcl HAM lhevdh ^ey ql_gby b kh^_j`Zl pbdebq_kdbc(CRC) bjh^v cbak e_lg ggc k l
^ey [Zclh\ - 7 HAM '6 % ]_g_jbjm_l pbdebq_kdbc dhgljhey ba[ulhqghklb
hibkZgguc \ jZa^gejZpby pbdebq_kdh]h dhgljhey ba[ulhqghklb
>ey aZibkb ^Zgguo \ [Zclu HAM bkihevamy Write Scratchpad [4Eh] ^Zgguo_ ^he`gu
[ulv i_j^Zgu dB20, gZqbgZy k [ZclZ Qlh[u d]h]j]_d]b]v]klv aZibkb g_Zhg]u]o]bfh
\uihegbly ql_g]bkihevamy dhfZg^mRead Scratchpad [BEh] ihke_lh]h dZd [mZ`ng]u_
aZibkZgh[jZlbl_\gbfZgb_ qlh ijb ql_g]bb %ZgguoZ_qbgZ_l i_j^Z\ZclZ Qlh[u
khojZgbTL, TL b ^Zgguo_]bkljZ dhgnb]mjZp EEPROM, mkljhckl\h mijZ\e_gb_\u^Zlgh
dhfZg Copy Scratchpad [48h].
>ZggukhojZg_ggu_ \ j_ EEPROM ijb \dexq_gbb iblZg]Z]jm`Zxlky \ HAM
>Zgguo_ fh]ml [ulv i_j_aZ] EEPROM baHAM \_ex[h_ \j_fy d Read [B8h].
Mkljhckl\h mijZ\e_gby fh`_l dhgljheb]h\RevalHE [B8]x ijhp_kk \uah\Z ^Zgguo
EEPROM \ HAM i m l k b f g o j h b f r z e i h k z e dhfZg^u b dhgljhey kthg]u]h]g]by
hi_jZpby i_j_aZ]jm]a]d`Z_lkykeb ijhp_kk \uiheg_g
    
```



```

l_jbf_j ijh]jZffu ^e16 ^ey jZ[hlu k h^gbf mkljhckl\hf gZ ebgbb
;=====
                                ql_gb_ l_fi_jZl
celsio                                ;
;=====
    baf_j_gb_ l_fi_jZlmju                                ;
        call    DOUT_LOW                                kehl ql_gby ^ey dhgljhey
        call    DOUT_HIGH                                hdhgqZgby dhg\_jlbjh\Zgby
        btfss   DALLAS                                ;
    return                                           ;
        btfsc   CON                                    ;
    goto    ctenie                                    ;
        call    RESET_DALLAS                            ;
        btfsc   ERROR_D                                ;
    return                                           ^Zlqbd g_bkijZ\_g ij\_jZlv dhg\_jlbjh\Zgb_ l_fi
;=====
        movlw   H'CC'                                    ; nhjfbjh\Zl\hfZg^m ljhimROMlv
        call    DSEND                                    ;
        movlw   H'44'                                    ; nhjfbjh\Zl\hfZg^m Dhg\_jlbjh\Zlv l_fi_jZlm
        call    DSEND                                    ;
;=====
        bsf     CON                                    b^_l dhg\_jlbjh\Zgb_
    return                                           ;
;=====
ctenie                                ql_gb_ l_fi_jZlmju
        bcf     CON                                    ; dhg\_jlbjh\Zgb_ \uiheg_gh
;=====
        call    RESET_DALLAS                            ;
        btfsc   ERROR_D                                ;
    return                                           ^Zlqbd g_bkijZ\_g ij\_jZlvfi_jZlmju
        movlw   H'CC'                                    ; ihkeZlv dhfZg^m ljhimROMkiblv
        call    DSEND                                    ;
        movlw   H'BE'                                    ; ihkeZlv dhfZg^m ql_gby iZfylyb
        call    DSEND                                    ;
        call    DRECEIVE                                qbIZlv [Zcl
        movf    COM_REG,W                                ;
        movwf   TEMP_LO                                ;
        call    DRECEIVE                                qbIZlv [Zcl
        movf    COM_REG,W                                ;
        movwf   TEMP_HI                                ;
    return                                           ;

```

Запись в память [4Eh]

```

WIZ dhfZg^Z iha\hey_l mkljhckl\m mijZ\e_gby aZibku\Zlv [ZclZ ^Zgguo \iZ
l_j\uc [Zcl ^Zgguo aZibku\Z_lkyTH j\_j\bklijhc [Zcl aZibku\Z\_lky b ljj\_j\bklij
[Zcl aZibku\Z\_lky \_j\_j]bklij dhgnb]mjZpbb
>Zggu_ ^he`gu [ulv i_j^Zgu gZbf_gvrbf agZqZsbf [blhf \i_j_
>ey ^Zlqbdh\ l_fi_jZlmju k iZjZablguf iblZgb_f \k_ ljb [ZclZ >HE@GU [ulv
DHIBJH<:GB? HAM <hIAM`>_ q_f mkljhckl\hf mijZ\e_gby [m^_l k]_g_jbjh\Zg b
bgZq_ ^Zggu_ [m^ml ihl_jygu

```

Чтение памяти [BEh]

```

WIZ dhfZg^Z iha\hey_l mkljhckl\h mijZ\e_gbyZlv kh^_j`Zgb_ l:FYLB l_j^ZqZ
gZqbgZ_lky k gZbf_gvr_]h agZqZs_]h [bIZ [ZclZ h]hijZbeZ[Zcl b]re bq_kdbc
dhgljhev ba[ulhqghklb Mkljhckl\hf mijZ\e_gbylv k[jhk qlh[u aZdhgqblv ql_gb
\j_fy _keb g_h[oh^bfh lhevdh qZklv ^Zgguo

```


DS18B20 OPERATION EXAMPLE 2

< wlfh jbf_bkihevam_lkvevdh h^bg '6 % gZk rbZjZablg uZfIZg b_ Mkljhckl\h
 mijZ\e_gby ihk uZg gL(TH, TL, and config) dj_]bkljZf dhgnb]mjZfAM '6 % aZ_f qblZ_l
 HAMh\lhjgh \uqbkbeyebq_kdbc dhgljhev ba[uihqghklb qh[u_ jZ_e_jblmk\Zlgk\h
 mijZ\e_gbyibjm_l kh^_j^ZAM EEPROM.

MASTER MODE	DATA (LSB FIRST)	COMMENTS
TX	Reset	Master issues reset pulse.
RX	Presence	DS18B20 responds with presence pulse.
TX	CCh	Master issues Skip ROM command.
TX	4Eh	Master issues Write Scratchpad command.
TX	3 data bytes	Master sends three data bytes to scratchpad (TH, TL, and config).
TX	Reset	Master issues reset pulse.
RX	Presence	DS18B20 responds with presence pulse.
TX	CCh	Master issues Skip ROM command.
TX	BEh	Master issues Read Scratchpad command.
RX	9 data bytes	Master reads entire scratchpad including CRC. The master then recalculates the CRC of the first eight data bytes from the scratchpad and compares the calculated CRC with the read CRC (byte 9). If they match, the master continues; if not, the read operation is repeated.
TX	Reset	Master issues reset pulse.
RX	Presence	DS18B20 responds with presence pulse.
TX	CCh	Master issues Skip ROM command.
TX	48h	Master issues Copy Scratchpad command.
TX	DQ line held high by strong pullup	Master applies strong pullup to DQ for at least 10ms while copy operation is in progress.

Приложение.

l jbf_jih^ijh]jZffgZZkk_f[e_ey k_PIC b lZdlh\hc f=p ih^jZamf_\Z_lky bkihe
 \gmlj_gg_]h]_g_jZffZ ijh]jZffZ ijb_\u_rgZ^ey ql_gby ^\mo [Zcl l_fi_jZlmju [_a
 ^hklh_jghklb ^Zgguo

```

=====
;DOUT_LOW WIZ ih^ijh]jZffZ mklZgZ\eb\Z_l ebgbx >:EE:KKZ gZ \u\h^"0" mklZgZ
DOUT_LOW
                bcf          DALLAS                mklZgh\biv gbadbc mjh\_gv gZ
                bsf          STATUS,RP0            \u[jZlv [Zgd
                bcf          TRISDAL,LINE          gZkljhblv ihjl gZ \uoh^
                bcf          STATUS,RP0            \u[jZlv [Zgd
                nop
                nop
                retlw .0
=====
    
```

Примечание: обратите особое внимание на формирование импульса восстановления DOUT_HIGH, это так называемый «Активный» импульс восстановления, когда на стандартное заданное время в линию для восстановления уровня закачивается ток с порта контроллера. Этот эффект позволяет значительно улучшить фронт сигнала. Формирование фронтов таким образом - это гарантия работы на удаленные датчики!!!

'287B+,*+ WIZ ih^ijh]jZffZ mklZgZ\eb\Z_l ebgbx >:EE:KKZ dZd \h^ ijh^Z\eb
 mjh_g_f rbgm
 Z aZl_f_i\h^bl ebgbx gZ ijb_f \g_rgbc j_abklhj m^_j`b\Z_l \ukhdbc mjh_gv

